

Multi-Task Sparsity via Maximum Entropy Discrimination

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Generative Learning

- Given $\mathcal{D} = (\mathbf{x}_t, y_t)_{t=1}^T$ sampled *iid* from unknown $P(\mathbf{x}, y)$
- Find rule producing \hat{y} from \mathbf{x} with low error

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- Generative Bayesian approach:
 - Assume $p(\mathbf{x}, y|\Theta)$ and $p(\Theta)$
 - Get $p(\Theta|\mathcal{D}) \propto \prod_{t=1}^T p(\mathbf{x}_t, y_t|\Theta)p(\Theta)$
 - Predict $\hat{y} = \arg \max_y \int_{\Theta} p(\mathbf{x}, y|\Theta)p(\Theta|\mathcal{D})$

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- Conditional Bayesian approach:
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 - Predict $\hat{y} = \arg \max_y \int_{\Theta} p(y|\mathbf{x}, \Theta)p(\Theta|\mathcal{D})$
- Problem: high test error when assumptions are wrong!
- Solution: add task constraint that correct y_t wins by margin γ

Discriminating with Task Constraints

Conditional Bayes, $\hat{y} = \arg \max_y \int_{\Theta} q(\Theta) p(y|\mathbf{x}, \Theta)$ via

$$\min_{q(\Theta)} \mathcal{KL} \left(q(\Theta) \parallel \frac{1}{Z} \prod_{t=1}^T p(y_t | \mathbf{x}_t, \Theta) p(\Theta) \right)$$

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Discriminating with Task Constraints

Log Conditional Bayes, $\hat{y} = \arg \max_y \int_{\Theta} q(\Theta) \ln p(y|\mathbf{x}, \Theta)$ via

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$$\min_{q(\Theta)} \mathcal{KL} \left(q(\Theta) \parallel \frac{1}{Z} \prod_{t=1}^T p(y_t | \mathbf{x}_t, \Theta) p(\Theta) \right) + C \sum_{t=1}^T \xi_t$$

$$\text{s.t. } \int_{\Theta} q(\Theta) \ln p(y_t | \mathbf{x}_t, \Theta) \geq \max_{y \neq y_t} \int_{\Theta} q(\Theta) \ln p(y | \mathbf{x}_t, \Theta) + \gamma - \xi_t \quad \forall t$$

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Easy, Maximum Entropy Discrimination (Jaakkola Meila Jebara 99)
 Slack allows some misclassification of training data

Primal and Dual MED

Primal

$$\min_{q(\Theta)} \mathcal{KL}(q(\Theta) \| \hat{p}(\Theta)) + C \sum_{t=1}^T \xi_t$$

$$s.t. \int_{\Theta} q(\Theta) \ln p(y_t | \mathbf{x}_t, \Theta) \geq \max_{y \neq y_t} \int_{\Theta} q(\Theta) \ln p(y | \mathbf{x}_t, \Theta) + \gamma - \xi_t \quad \forall t$$

Dual

$$\max_{\lambda \in [0, C]} -\ln \int_{\Theta} \hat{p}(\Theta) \prod_{t=1}^T \left(\frac{p(y_t | \mathbf{x}_t, \Theta)}{\max_{y \neq y_t} p(y | \mathbf{x}_t, \Theta)} \right)^{\lambda_t} \exp(-\gamma \lambda_t)$$

$$q(\Theta) = \frac{1}{Z(\lambda)} \hat{p}(\Theta) \prod_{t=1}^T \left(\frac{p(y_t | \mathbf{x}_t, \Theta)}{\max_{y \neq y_t} p(y | \mathbf{x}_t, \Theta)} \right)^{\lambda_t} \exp(-\gamma \lambda_t)$$

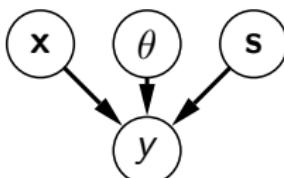
MED for Support Vector Machines

- Set $p(y|\mathbf{x}, \Theta) \propto \exp(y/2(\mathbf{x}^\top \theta + b))$ and $\Theta = \{\theta, b\}$
- Set $\hat{p}(\Theta) = \mathcal{N}(b|0, \infty) \mathcal{N}(\theta|\mathbf{0}, \mathbf{I})$
- MED dual produces support vector machine optimization

$$\max_{\substack{\lambda \in [0, C] \\ \sum_i y_i \lambda_i = 0}} \gamma \sum_i \lambda_i - \frac{1}{2} \sum_{ij} \lambda_i \lambda_j y_i y_j \mathbf{x}_i^\top \mathbf{x}_j$$

- MED prediction becomes the same
 $\hat{y} = \text{sign} \left(\sum_t y_t \lambda_t \mathbf{x}_t^\top \mathbf{x} + b \right)$
- Solvable in $\mathcal{O}(T^3)$ with quadratic programming
- Faster solution to ϵ accuracy with e.g. Pegasos

MED for Feature Selection

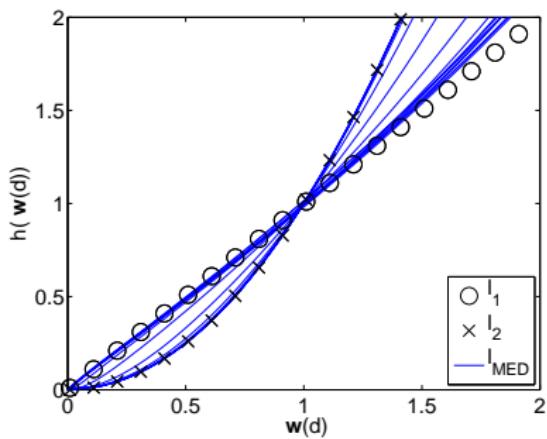


- Model $\Theta = \{\theta, b, \mathbf{s}\}$ where $\mathbf{s} \in \mathbb{B}^D$ sparsifies $\theta \in \mathbb{R}^D$
- Set $p(y|\mathbf{x}, \Theta, \mathbf{s}) \propto \exp(y/2(\sum_d \mathbf{s}(d)\mathbf{x}(d)\theta(d) + b))$
- Set $\hat{p}(\Theta) = \mathcal{N}(b|0, \infty) \mathcal{N}(\theta|\mathbf{0}, \mathbf{I}) \prod_d \rho^{\mathbf{s}(d)}(1 - \rho)^{1 - \mathbf{s}(d)}$
- Parameter ρ (or $\alpha = \frac{1-\rho}{\rho}$) is prior % of non-sparse features
- MED dual is

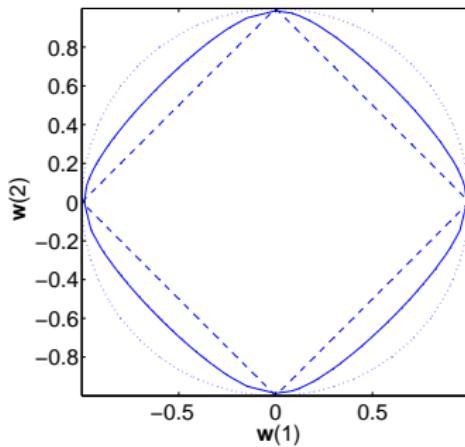
$$\max_{\substack{\lambda \in [0, C] \\ \sum_i y_i \lambda_i = 0}} \gamma \sum_i \lambda_i - \sum_{d=1}^D \ln \left(\alpha + e^{\frac{1}{2} \sum_{ij} y_i y_j \lambda_i \lambda_j \mathbf{x}_i(d) \mathbf{x}_j(d)} \right)$$

- MED prediction is $\hat{y} = \text{sign} (\sum_{di} y_i \lambda_i \mathbf{x}_i(d) \mathbf{x}_j(d) \hat{\mathbf{s}}(d) + b)$
where $\hat{\mathbf{s}}(d) = \left(1 + \alpha \exp(-\frac{1}{2} \sum_{ij} y_i y_j \lambda_i \lambda_j \mathbf{x}_i(d) \mathbf{x}_j(d)) \right)^{-1}$

MED for Feature Selection



(a) One dimensional plot



(b) Two dimensional contour plot

Figure: (a) Various norms on the weight vector shown as α varies from $\alpha = 0$ which mimics an ℓ_2 norm to α large which mimics an ℓ_1 norm. (b) a two-dimensional contour plot of the ℓ_1 penalty (dot-dash line), the ℓ_2 penalty (dotted line) and the ℓ_{MED} penalty with $\alpha = 2$ (solid line).

MED for Feature Selection

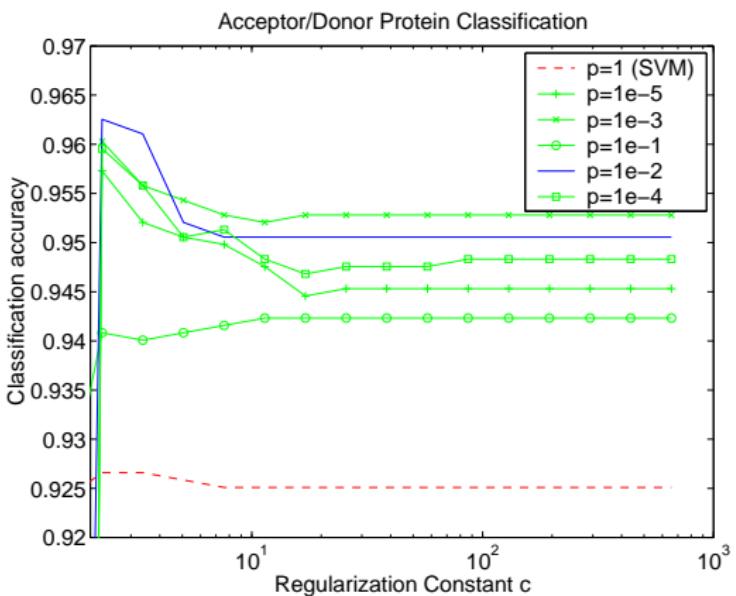
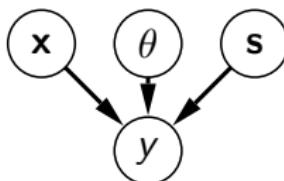


Figure: Acceptor/donor sequence classification accuracy.

MED for Kernel Selection

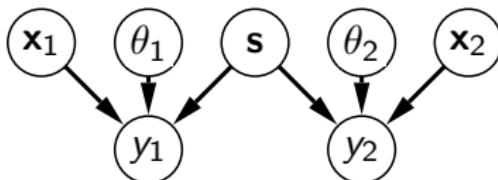


- Select from $\phi_1(\mathbf{x}), \dots, \phi_D(\mathbf{x})$ mappings to Hilbert space
- Model $\Theta = \{\theta_1, \dots, \theta_D, b, \mathbf{s}\}$ where $\mathbf{s} \in \mathbb{B}^D$ selects $\theta_d \in \mathcal{H}$
- Set $p(y|\mathbf{x}, \Theta, \mathbf{s}) \propto \exp(y/2(\sum_d \mathbf{s}(d)\theta_d^\top \phi_d(\mathbf{x}) + b))$
- MED dual is

$$\max_{\substack{\lambda \in [0, C] \\ \sum_i y_i \lambda_i = 0}} \gamma \sum_i \lambda_i - \sum_{d=1}^D \ln \left(\alpha + e^{\frac{1}{2} \sum_{ij} y_i y_j \lambda_i \lambda_j k_d(\mathbf{x}_i, \mathbf{x}_j)} \right)$$

- MED prediction is $\hat{y} = \text{sign}(\sum_{di} y_i \lambda_i \hat{\mathbf{s}}(d) k_d(\mathbf{x}, \mathbf{x}_i) + b)$ where $\hat{\mathbf{s}}(d) = \left(1 + \alpha \exp(-\frac{1}{2} \sum_{ij} y_i y_j \lambda_i \lambda_j k_d(\mathbf{x}, \mathbf{x}_i))\right)^{-1}$

Multi-Task Margin Constraints for Kernel Selection



- Have M models $\Theta = \{\Theta_1, \dots, \Theta_M, \mathbf{s}\}$ and sparsifier $\mathbf{s} \in \mathbb{B}^D$
- Each model is $\Theta_m = \{\theta_{m1}, \dots, \theta_{mD}, b_m\}$
- Set $p(y|\mathbf{x}, \Theta_m, \mathbf{s}) \propto \exp(y/2(\sum_d \mathbf{s}(d)\theta_{md}^\top \phi_d(\mathbf{x}) + b_m))$
- MED dual is

$$\max_{\substack{\lambda \in [0, C] \\ \sum_i y_{mi} \lambda_{mi} = 0}} \gamma \sum_{mi} \lambda_{mi} - \sum_{d=1}^D \ln \left(\alpha + e^{\frac{1}{2} \sum_{mij} y_{mi} y_{mj} \lambda_{mi} \lambda_{mj} k_d(\mathbf{x}_{mi}, \mathbf{x}_{mj})} \right)$$

- Task m predicts $\hat{y} = \text{sign}(\sum_{di} y_{mi} \lambda_{mi} \hat{\mathbf{s}}(d) k_d(\mathbf{x}, \mathbf{x}_{mi}) + b_m)$
- $\hat{\mathbf{s}}(d) = \left(1 + \alpha \exp(-\frac{1}{2} \sum_m \sum_{ij} y_{mi} y_{mj} \lambda_{mi} \lambda_{mj} k_d(\mathbf{x}_{mi}, \mathbf{x}_{mj})) \right)^{-1}$

Multi-Task Margin Constraints for Kernel Selection

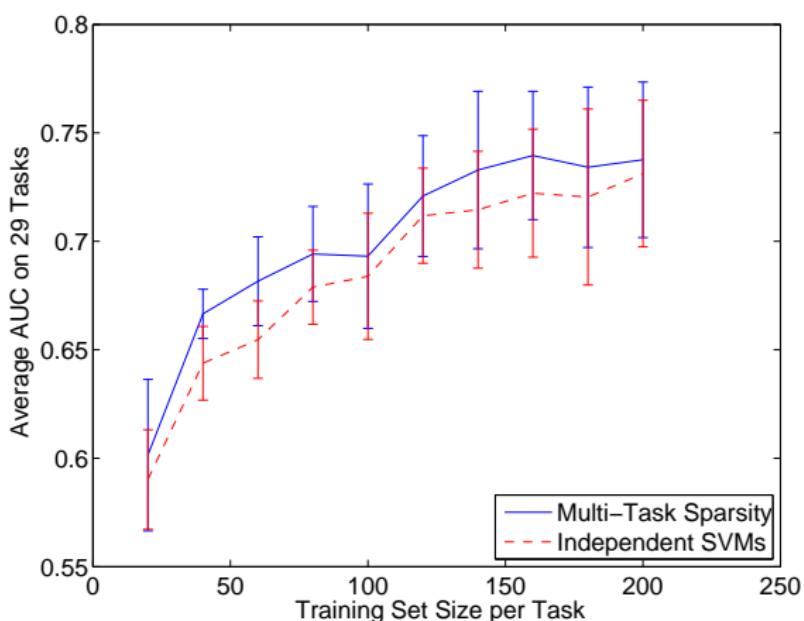


Figure: Feature and RBF kernel selection on the Landmine dataset (Xue Liao Carin Krishnapuram 07). Values for C and α obtained by cross-validation on held out data.

Sequential Quadratic Programming

- How to optimize MED when it's not a QP? For example,
$$\max_{\lambda \in [0, C], \sum_i y_i \lambda_i = 0} \gamma \sum_i \lambda_i - \sum_{d=1}^D \ln \left(\alpha + e^{\lambda^\top H \lambda} \right)$$
- Lower bound – \ln terms with a quadratic, get sequential QP

Theorem (Jebara 11)

For any \mathbf{v} , the term $-\ln \left(\alpha + e^{\mathbf{u}^\top \mathbf{u}} \right)$ is lower bounded by

$$-\ln \left(\alpha + e^{\mathbf{v}^\top \mathbf{v}} \right) - 2 \frac{\mathbf{v}^\top (\mathbf{u} - \mathbf{v})}{\alpha e^{-\mathbf{v}^\top \mathbf{v}} + 1} - (\mathbf{u} - \mathbf{v})^\top \left(\mathcal{G} \mathbf{v} \mathbf{v}^\top + I \right) (\mathbf{u} - \mathbf{v})$$

when $\mathcal{G} \geq \frac{\tanh(\frac{1}{2} \ln(\alpha \exp(-\mathbf{v}^\top \mathbf{v})))}{\ln(\alpha \exp(-\mathbf{v}^\top \mathbf{v}))}$.

Sequential Quadratic Programming

0	Input: dataset \mathcal{D} , $C > 0$, $\alpha \geq 0$, $0 < \epsilon < 1$
1	Initialize Lagrange multipliers to zero, $\lambda = \mathbf{0}$.
2	Store $\tilde{\lambda} = \lambda$.
3	Apply bound on all $-\ln(\alpha + e^{\lambda^\top H \lambda})$ terms at $\tilde{\lambda}$.
4	Solve resulting (fast) SVM problem to get λ .
5	If $\ \lambda - \tilde{\lambda}\ > \epsilon \ \lambda\ $ go to 2.
6	Output λ .

Theorem (Jebara 11)

SQP achieves $(1 - \epsilon)J(\lambda^*)$ within $\left\lceil \frac{\log(1/\epsilon)}{\log(\min(1 + \frac{1}{\alpha}, 2))} \right\rceil$ iterations.

Sparse multi-task is a constant factor more work than SVMs.

Sequential Quadratic Programming

Proof.

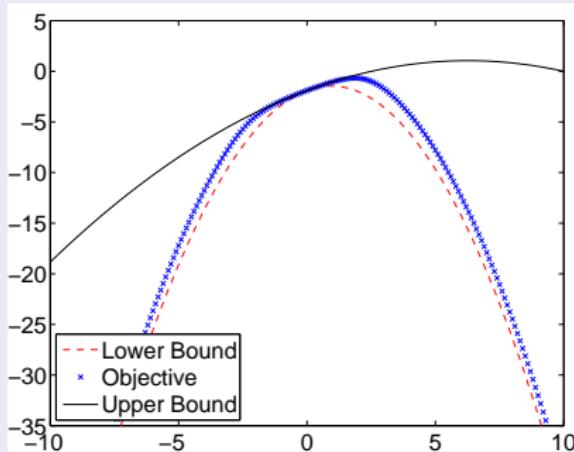
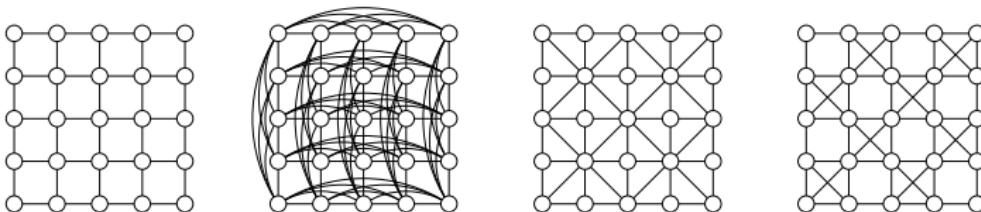


Figure: Quadratic bounding sandwich. Compare upper and lower bound curvatures to bound maximum # of iterations.



Graphical Model Structure Estimation



- Consider an Ising model with distribution $p(\mathbf{x})$ proportional to

$$\exp \left(\sum_{m=1}^D \eta(m) \mathbf{x}(m) + \sum_{m=1}^D \sum_{n=1}^D \mathbf{s}(m, n) \theta(m, n) \mathbf{x}(m) \mathbf{x}(n) \right)$$

- $\mathbf{s} \in \mathbb{B}^{D \times D}$ a symmetric matrix with zero on its diagonal
 - $\theta \in \mathbb{R}^{D \times D}$ is a symmetric matrix with zero on its diagonal
 - $\eta \in \mathbb{R}^D$ a vector
- Goal: given T binary vectors $\mathbf{x}_1, \dots, \mathbf{x}_T$ where $\mathbf{x}_t \in \mathbb{B}^D$ sampled *iid* from an unknown $p(\mathbf{x})$ find $\hat{\mathbf{s}}$

Graphical Model Structure Estimation

- Recall ℓ_1 method of Wainwright Ravikumar Lafferty 07
- Recover $\hat{\mathbf{s}}$ by solving D ℓ_1 sparse regressions

$$\min_{\theta \in \mathbb{R}^D} \nu \sum_{d \neq m} |\theta(d)| + \sum_{t=1}^T \log(1 + e^{\sum_{d \neq m} \theta(d) \mathbf{x}_t(d) + \theta(m)}) - \mathbf{x}_t(m) \left(\sum_{d \neq m} \theta(d) \mathbf{x}_t(d) + \theta(m) \right)$$

- Learn to regress each dimension from all others
- Symmetrize by $\hat{\mathbf{s}}(m, n) = \lceil \hat{\theta}_m(n) \hat{\theta}_n(m) \rceil$ (AND operation)
- Symmetrize by $\hat{\mathbf{s}}(m, n) = \lceil \hat{\theta}_m(n) + \hat{\theta}_n(m) \rceil$ (OR operation)
- Both have nice asymptotic consistency properties

Graphical Model Structure Estimation

- How to symmetrize *during* learning in Wainwright et al. ?
- MED approach: assume the following predictive distribution

$$p(y|m, \mathbf{x}, \theta, b, \mathbf{s}) \propto \exp\left(\frac{y}{2} \sum_{d \neq m} \mathbf{s}(m, d) \mathbf{x}(d) \theta(m, d) + b(m)\right)$$

- Use sparse symmetric Bernoulli prior on \mathbf{s}
- Use Gaussian prior on θ allowing it to be asymmetric
- MED's dual is a single joint constrained convex optimization

$$\max_{\lambda \in \Lambda} \lambda^\top \mathbf{1} - \sum_{m=1}^D \sum_{d=m+1}^D \log \left(\alpha + e^{\frac{1}{2} \lambda^\top H_{m,d} \lambda} \right)$$

- Solve with bound and sequential quadratic programming

Graphical Model Structure Estimation

- Symmetrizing the graph structure via MED helps!

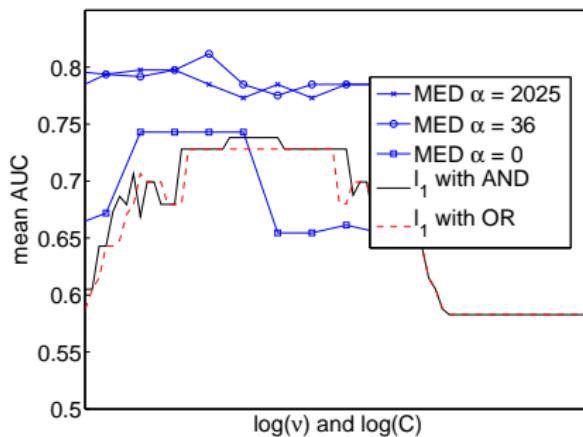


Figure: Graphical model structure recovery from synthetic experiments

Relative Margin Constraints

- Why stop with just γ classification constraints?
- Limit spread between correct to weakest by β constraint
- Relative margin machines (Shivaswamy & Jebara 10)

$$\min_{q(\Theta)} \mathcal{KL}(q(\Theta) \| \hat{p}(\Theta))$$

$$s.t. \int_{\Theta} q(\Theta) \ln p(y_t | \mathbf{x}_t, \Theta) \geq \max_{y \neq y_t} \int_{\Theta} q(\Theta) \ln p(y | \mathbf{x}_t, \Theta) + \gamma \quad \forall t$$

$$s.t. \int_{\Theta} q(\Theta) \ln p(y_t | \mathbf{x}_t, \Theta) \leq \min_{y \neq y_t} \int_{\Theta} q(\Theta) \ln p(y | \mathbf{x}_t, \Theta) + \beta \quad \forall t$$

- The SVM optimization (with slack omitted) then becomes

$$\min_{\mathbf{w}, b} \frac{1}{2} \|\mathbf{w}\|^2 \text{ subject to } \beta \geq y_i (\mathbf{w}^\top \mathbf{x}_i + b) \geq \gamma$$

Relative Margin Constraints

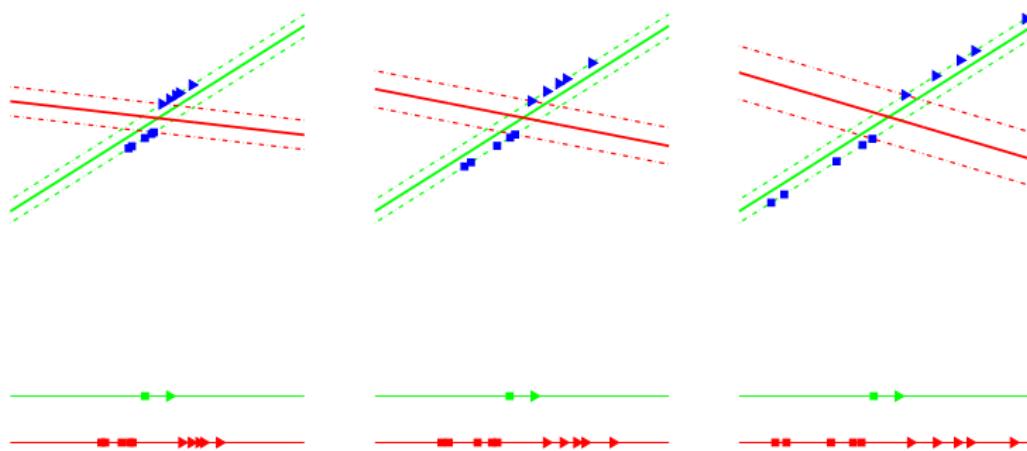


Figure: Top: As the data is scaled, the SVM (red or dark shade) deviates from the RMM (green or light shade). Bottom: The projections of the examples (that is $\mathbf{w}^\top \mathbf{x} + b$) on the real line for the SVM and the RMM.

Relative Margin Constraints in Binary Classification

Dataset	SVM	KFDA	Σ -SVM	RMM (C=D)	RMM
banana	10.5 ± 0.4	10.8 ± 0.5	10.5 ± 0.4	10.4 ± 0.4	$10.4 \pm 0.4^*$
b.cancer	$25.3 \pm 4.6^*$	26.6 ± 4.8	28.8 ± 4.6	25.9 ± 4.5	27.2 ± 4.8
diabetes	23.1 ± 1.7	23.2 ± 1.8	24.2 ± 1.9	23.1 ± 1.7	$23.0 \pm 1.7^*$
f.solar	32.3 ± 1.8	33.1 ± 1.6	34.6 ± 2.0	$32.3 \pm 1.8^*$	33.1 ± 2.5
german	23.4 ± 2.2	24.1 ± 2.4	25.9 ± 2.4	23.4 ± 2.1	$23.2 \pm 2.2^*$
heart	15.5 ± 3.3	15.7 ± 3.2	19.9 ± 3.6	15.4 ± 3.3	$15.2 \pm 3.1^*$
image	3.0 ± 0.6	3.1 ± 0.6	3.3 ± 0.7	3.0 ± 0.6	2.9 ± 0.7
ringnorm	1.5 ± 0.1	1.5 ± 0.1	1.5 ± 0.1	1.5 ± 0.1	$1.5 \pm 0.1^*$
splice	10.9 ± 0.7	10.6 ± 0.7	10.8 ± 0.6	10.8 ± 0.6	10.8 ± 0.6
thyroid	4.7 ± 2.1	4.2 ± 2.1	4.5 ± 2.1	$4.2 \pm 1.8^*$	4.2 ± 2.2
titanic	22.3 ± 1.1	$22.0 \pm 1.3^*$	23.1 ± 2.2	22.3 ± 1.1	22.2 ± 1.3
twonorm	2.4 ± 0.1	2.4 ± 0.2	2.5 ± 0.2	2.4 ± 0.1	$2.3 \pm 0.1^*$
waveform	9.9 ± 0.4	9.9 ± 0.4	10.5 ± 0.5	10.0 ± 0.4	$9.7 \pm 0.4^*$

Relative Margin Constraints in Structured Prediction

MED extended to structured prediction (Zhu & Xing 09)

Add relative margin to structured prediction (Shivaswamy & J 09)
 Multi-class classification error

Kernel	StructSVM	StructRMM	p-value
Poly 1	3.78 ± 0.54	3.85 ± 0.62	0.55
Poly 2	2.11 ± 0.43	1.46 ± 0.34	0.00
Ploy 3	1.73 ± 0.37	1.24 ± 0.43	0.00
Poly 4	1.55 ± 0.45	1.18 ± 0.43	0.00

Sequence label error (Named Entity Rec. & Part of Speech)

	CRF	StructSVM	StructRMM	p-value
NER	5.13 ± 0.28	5.09 ± 0.32	5.05 ± 0.28	0.07
POS	11.34 ± 0.64	11.14 ± 0.60	10.42 ± 0.47	0.00

Conclusions

- Added task-relevant margin constraints in generative learning
- We call this Maximum Entropy Discrimination
- Straightforward multi-task feature and kernel selection
- Produces sparse symmetric graphical model structure
- A blend between ℓ_1 and ℓ_2 norms
- Optimizations via sequential quadratic programming
- Only constant time more work than SVM
- Relative margin constraints yield further improvements